

# Digital Logic Design: a rigorous approach ©

## Chapter 13: Decoders and Encoders

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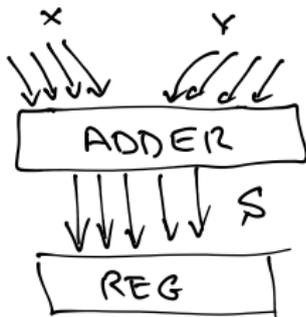
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Book Homepage:

<http://www.eng.tau.ac.il/~guy/Even-Medina>

## Example

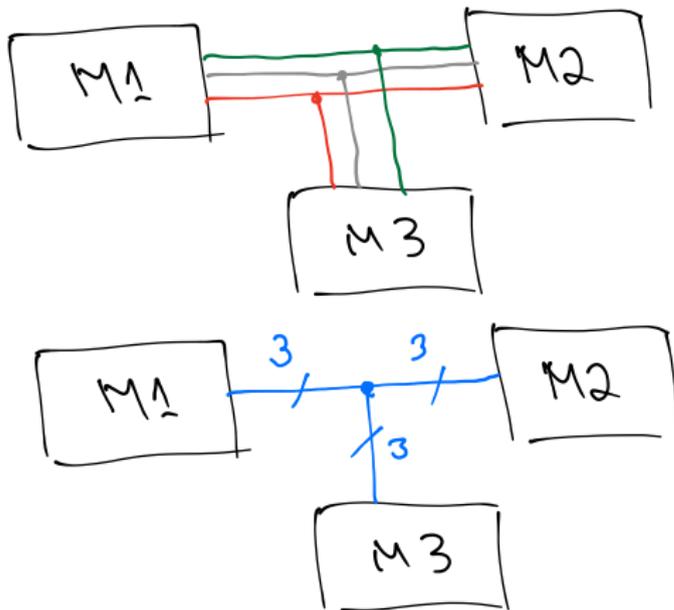
An adder and a register (a memory device). The output of the adder should be stored by the register. Different name to each bit?!



$$\langle S \rangle = \langle X \rangle + \langle Y \rangle$$

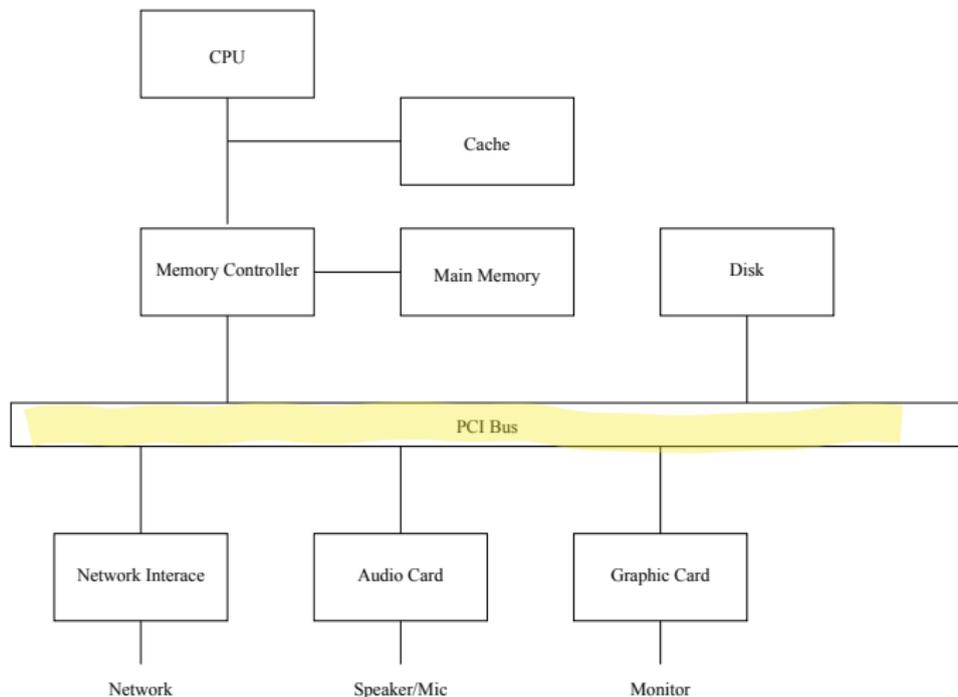
## Definition

A *bus* is a set of nets that are connected to the same modules. The *width* of a bus is the number of nets in the bus.

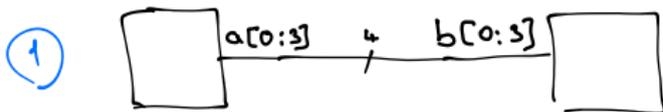


## Example

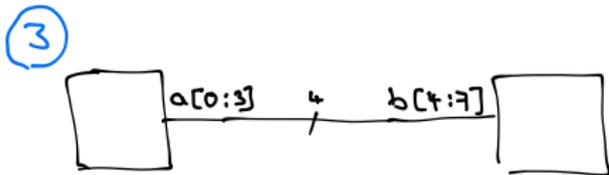
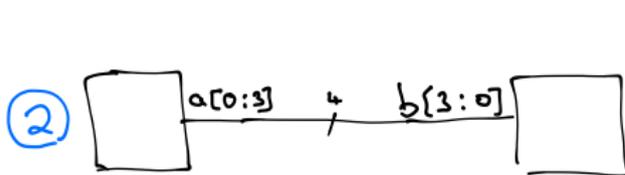
PCI bus is data network that connects modules in a computer system.



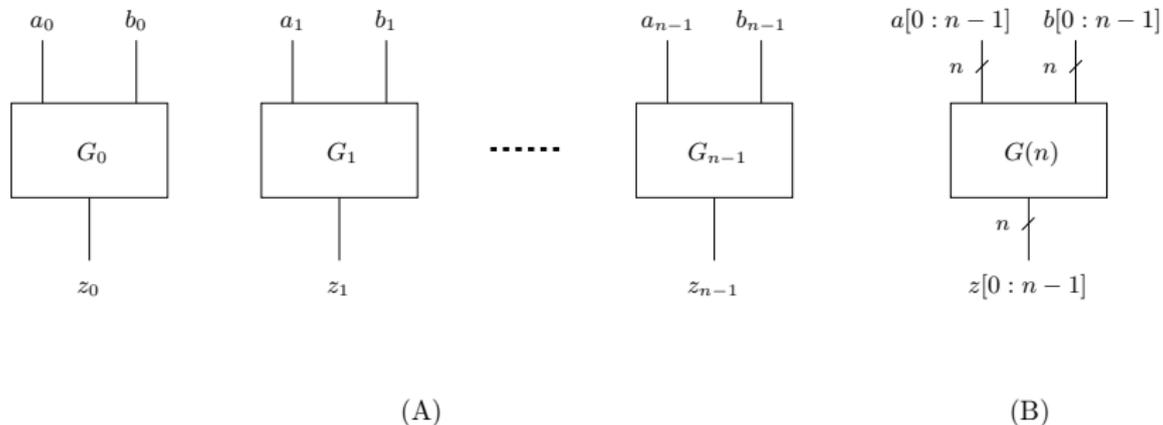
# Indexing conventions



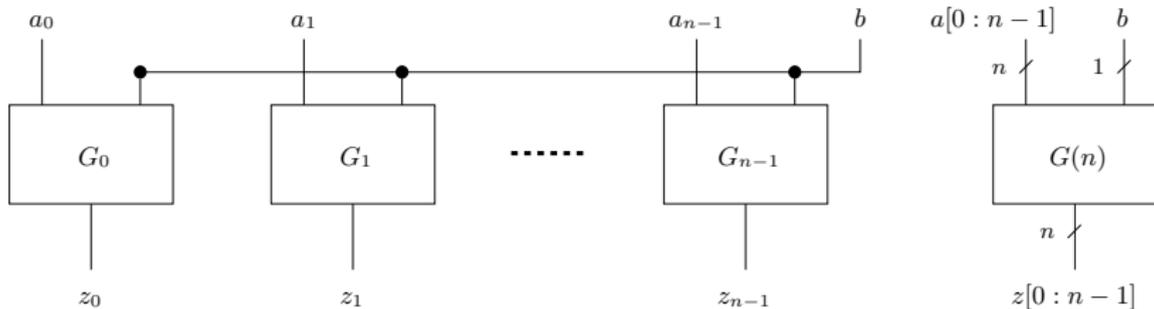
- ① Connection of terminals is done by assignment statements: The statement  $b[0 : 3] \leftarrow a[0 : 3]$  means connect  $a[i]$  to  $b[i]$ .
- ② “Reversing” of indexes does not take place unless explicitly stated:  $b[i : j] \leftarrow a[i : j]$  and  $b[i : j] \leftarrow a[j : i]$ , have the same meaning, i.e.,  $b[i] \leftarrow a[i], \dots, b[j] \leftarrow a[j]$ .
- ③ “Shifting” is done by default:  $a[0 : 3] \leftarrow b[4 : 7]$ , meaning that  $a[0] \leftarrow b[4], a[1] \leftarrow b[5]$ , etc. We refer to such an implied re-assignment of indexes as **hardwired shifting**.



# Example - 1



**Figure:** Vector notation: multiple instances of the same gate. (A) Explicit multiple instances (B) Abbreviated notation.



(A)

(B)

**Figure:** Vector notation:  $b$  feeds all the gates. (A) Explicit multiple instances (B) Abbreviated notation.

# Reminder: Binary Representation

Recall that  $\langle a[n-1 : 0] \rangle_n$  denotes the binary number represented by an  $n$ -bit vector  $\vec{a}$ .

$$\langle a[n-1 : 0] \rangle_n \triangleq \sum_{i=0}^{n-1} a_i \cdot 2^i.$$

## Definition

*Binary representation* using  $n$ -bits is a function  $bin_n : \{0, 1, \dots, 2^n - 1\} \rightarrow \{0, 1\}^n$  that is the inverse function of  $\langle \cdot \rangle$ . Namely, for every  $a[n-1 : 0] \in \{0, 1\}^n$ ,

$$bin_n(\langle a[n-1 : 0] \rangle_n) = a[n-1 : 0].$$

$$bin_3(2) = 010$$

# Division in Binary Representation

$$r = (a \bmod b):$$

$$a = q \cdot b + r, \text{ where } 0 \leq r < b.$$

## Claim

Let  $s = \langle x[n-1:0] \rangle_n$ , and  $0 \leq k \leq n-1$ . Let  $q$  and  $r$  denote the quotient and remainder obtained by dividing  $s$  by  $2^k$ . Define the binary strings  $x_R[k-1:0]$  and  $x_L[n-1:n-k-1]$  as follows.

$$S = q \cdot 2^k + r$$

$$x_R[k-1:0] \triangleq x[k-1:0]$$

$$x_L[n-k-1:0] \triangleq x[n-1:k].$$



Then,

$$q = \langle x_L[n-k-1:0] \rangle$$

$$r = \langle x_R[k-1:0] \rangle.$$

example (division by  $2^4$ )

$$X = \underbrace{1001}_{x_L} \underbrace{1110}_{x_R}$$

$$K = 4$$

$$\langle X \rangle = \langle 1001 \rangle \cdot 2^4 + \langle 1110 \rangle$$

# Multiplication

Multiplication of  $A[n - 1 : 0]$  by  $B[n - 1 : 0]$  in binary representation proceeds in two steps:

- compute all the partial products  $A[i] \cdot B[j]$
- add the partial products

$$\begin{array}{r} 1011 \\ \times 1110 \\ \hline 0000 \\ 1011 \\ 1011 \\ + 1011 \\ \hline 10011010 \end{array}$$

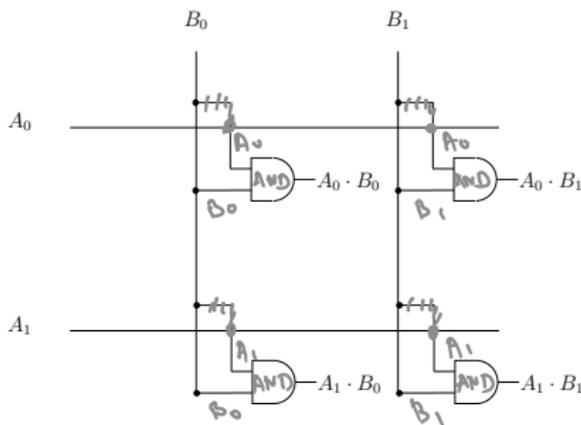
# Computation of Partial Products

Input:  $A[n-1:0], B[n-1:0] \in \{0,1\}^n$ .

Output:  $C[i,j] \in \{0,1\}^{n^2-1}$  where  $(0 \leq i,j \leq n-1)$

Functionality:  $C[i,j] = A[i] \cdot B[j]$

2x2  
array of  
AND



We refer to such a circuit as  $n \times n$  array of AND gates. Cost is  $n^2$  and delay equals 1 (Q: What is the lower bound?).

## Definition

A **decoder with input length  $n$**  is a combinational circuit specified as follows:

**Input:**  $x[n-1 : 0] \in \{0, 1\}^n$ .

**Output:**  $y[2^n - 1 : 0] \in \{0, 1\}^{2^n}$

**Functionality:**

$$y[i] \triangleq \begin{cases} 1 & \text{if } \langle \vec{x} \rangle = i \\ 0 & \text{otherwise.} \end{cases}$$

Number of outputs of a decoder is exponential in the number of inputs. Note also that exactly one bit of the output  $\vec{y}$  is set to one. Such a representation of a number is often termed **one-hot encoding** or **1-out-of- $k$  encoding**.

# Definition of Decoder

## Definition

A **decoder with input length  $n$** :

**Input:**  $x[n-1:0] \in \{0,1\}^n$ .

**Output:**  $y[2^n-1:0] \in \{0,1\}^{2^n}$

**Functionality:**

$$y[i] \triangleq \begin{cases} 1 & \text{if } \langle \vec{x} \rangle = i \\ 0 & \text{otherwise.} \end{cases}$$

We denote a decoder with input length  $n$  by  $\text{DECODER}(n)$ .

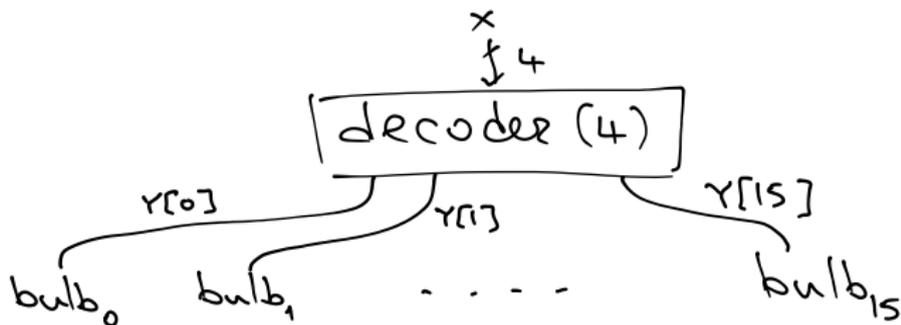
## Example

Consider a decoder  $\text{DECODER}(3)$ . On input  $x = 101$ , the output  $y$  equals 00100000. ( $\langle x \rangle = 5$ )

7 6 5 4 3 2 1 0

# Application of decoders

An example of how a decoder is used is in decoding of controller instructions. Suppose that each instruction is coded by an 4-bit string. Our goal is to determine what instruction is to be executed. For this purpose, we feed the 4 bits to a `DECODER(4)`. There are 16 outputs, exactly one of which will equal 1. This output will activate a module that should be activated in this instruction.



# Brute force design

- simplest way: build a separate circuit for every output bit  $y[i]$ .
- The circuit for  $y[i]$  is simply a product of  $n$  literals.
- Let  $v \triangleq \text{bin}_n(i)$ , i.e.,  $v$  is the binary representation of the index  $i$ .  
 $v \in \{0,1\}^n, \langle v \rangle = i$
- define the minterm  $p_v$  to be  $p_v \triangleq (l_0^v \cdot l_1^v \cdots l_{n-1}^v)$ , where:

$$l_j^v \triangleq \begin{cases} x_j & \text{if } v_j = 1 \\ \bar{x}_j & \text{if } v_j = 0. \end{cases}$$

$y[\langle v \rangle] \leftarrow \text{AND}_n(l_0^v, \dots, l_{n-1}^v)$

## Claim

$y[i] = 1$  iff  ~~$\hat{\tau}_x(p_v) = 1$~~  ( ~~$p_v$  is satisfied by  $\tau_x$~~ ).

$$\langle x \rangle = i$$

$$y[\langle v \rangle] = \text{AND}_n (l_0^v, \dots, l_{n-1}^v)$$

example

$$x = 101$$

$$n = 3$$

$$\langle x \rangle = 5$$

$$v = 100$$

$$i = 4$$

$$p_v = x_2 \cdot \bar{x}_1 \cdot \bar{x}_0$$

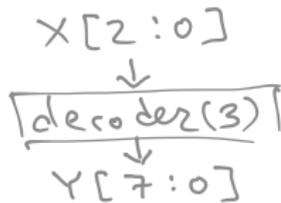
$$y[4] = 1 \cdot 1 \cdot 0 = 0$$

$$v = 101$$

$$i = 5$$

$$p_v = x_2 \cdot \bar{x}_1 \cdot x_0$$

$$y[5] = 1 \cdot 1 \cdot 1 = 1$$



proof:

$$y[i] = 1 \Leftrightarrow \langle x \rangle = i$$

for input  $x[n-1:0]$ ,

$$y[i] = 1 \Leftrightarrow \text{AND}_n(l_0^v, \dots, l_{n-1}^v) = 1 \quad (\langle v \rangle = i)$$

$$\Leftrightarrow \hat{c}_x(p_v) = 1$$

but

$$\hat{c}_x(p_v) = \begin{cases} 1 & \text{if } x = v \\ 0 & \text{o.w.} \end{cases}$$

$$\Leftrightarrow v = x$$

$$\Leftrightarrow i = \langle v \rangle = \langle x \rangle$$



The brute force decoder circuit consists of:

- $n$  inverters used to compute  $\text{INV}(\vec{x})$ , and
- a separate  $\text{AND}(n)$ -tree for every output  $y[i]$ .
- The delay of the brute force design is  $t_{pd}(\text{INV}) + t_{pd}(\text{AND}(n)\text{-tree}) = O(\log_2 n)$ .
- The cost of the brute force design is  $\Theta(n \cdot 2^n)$ , since we have an  $\text{AND}(n)$ -tree for each of the  $2^n$  outputs.

Wasteful because, if the binary representation of  $i$  and  $j$  differ in a single bit, then the  $\text{AND}$ -trees of  $y[i]$  and  $y[j]$  share all but a single input. Hence the product of  $n - 1$  bits is computed twice.

We present a systematic way to share hardware between different outputs.

$$y[\langle 0 \dots 0 \rangle] = \text{AND}_n(\bar{x}_0, \dots, \bar{x}_{n-2}, \bar{x}_{n-1})$$

$$y[\langle 0 \dots 01 \rangle] = \text{AND}_n(\bar{x}_0, \dots, \bar{x}_{n-2}, x_{n-1})$$

# An asymptotically optimal decoder design

## Base case $\text{DECODER}(1)$ :

The circuit  $\text{DECODER}(1)$  is simply one inverter where:

$y[0] \leftarrow \text{INV}(x[0])$  and  $y[1] \leftarrow x[0]$ .

## Reduction rule $\text{DECODER}(n)$ :

We assume that we know how to design decoders with input length less than  $n$ , and design a decoder with input length  $n$ .

$$\langle x \rangle = \langle x_L \rangle \cdot 2^k + \langle x_R \rangle$$

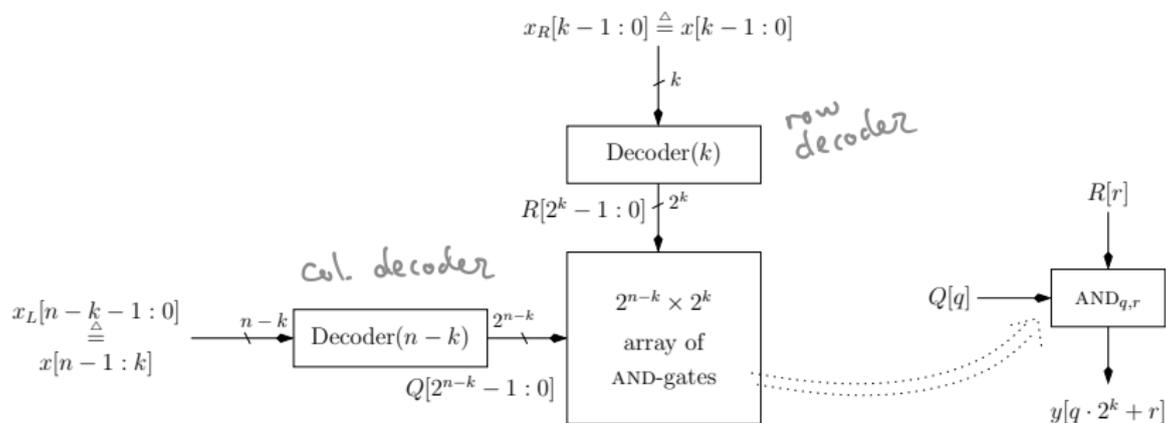


Figure: A recursive implementation of  $\text{DECODER}(n)$ .

### Claim (Correctness)

$$y[i] = 1 \iff \langle x[n-1:0] \rangle = i.$$

$$y[i] = 1 \Leftrightarrow \langle x \rangle = i$$

proof:

divide by  $2^k$

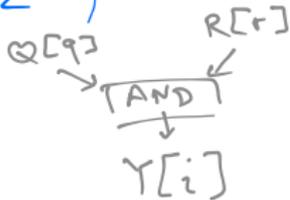
$$\langle x \rangle = \langle x_L \rangle \cdot 2^k + \langle x_R \rangle$$

now  $Q[j] = 1 \Leftrightarrow \langle x_L \rangle = j$  (ind. hyp. decoder(n-k))

$R[l] = 1 \Leftrightarrow \langle x_R \rangle = l$  (ind. hyp. decoder(k))

divide  $i = q \cdot 2^k + r$  ( $0 \leq r < 2^k$ )

$$Y[q \cdot 2^k + r] = 1$$



$$\Leftrightarrow Q[q] = R[r] = 1$$

$$\Leftrightarrow q = \langle x_L \rangle \text{ \& \& } r = \langle x_R \rangle$$

$$\Leftrightarrow q \cdot 2^k + r = \langle x_L \rangle 2^k + \langle x_R \rangle = \langle x \rangle$$



# Cost analysis

We denote the cost and delay of `DECODER`( $n$ ) by  $c(n)$  and  $d(n)$ , respectively. The cost  $c(n)$  satisfies the following recurrence equation:

$$c(n) = \begin{cases} c(\text{INV}) & \text{if } n=1 \\ c(k) + c(n-k) + 2^n \cdot c(\text{AND}) & \text{otherwise.} \end{cases}$$

It follows that, up to constant factors

$$c(n) = \begin{cases} 1. & \text{if } n = 1 \\ c(k) + c(n-k) + 2^n & \text{if } n > 1. \end{cases} \quad (1)$$

Obviously,  $c(n) = \Omega(2^n)$  (regardless of the value of  $k$ ).

## Claim

$c(n) = O(2^n)$  if  $k = \lceil n/2 \rceil$ .

## Cost analysis (cont.)

$$c(n) = \begin{cases} c(\text{INV}) & \text{if } n=1 \\ c(k) + c(n-k) + 2^n & \text{otherwise.} \end{cases}$$

### Claim

$$c(n) = O(2^n) \text{ if } k = \lceil n/2 \rceil.$$

### Proof.

$c(n) \leq 2 \cdot 2^n$  by complete induction on  $n$ .

- basis: check for  $n \in \{1, 2, 3\}$ .
- step: ( $n \geq 4$ )

Q: does it suffice to prove for  $n=2^l$ ?

$$\begin{aligned} c(n) &= c(\lceil n/2 \rceil) + c(\lfloor n/2 \rfloor) + 2^n \\ &\leq 2^{1+\lceil n/2 \rceil} + 2^{1+\lfloor n/2 \rfloor} + 2^n \\ &= 2 \cdot 2^n \cdot \underbrace{(2^{-\lfloor n/2 \rfloor} + 2^{-\lceil n/2 \rceil} + 1/2)}_{\leq 1} \end{aligned}$$



The delay of  $\text{DECODER}(n)$  satisfies the following recurrence equation:

$$d(n) = \begin{cases} d(\text{INV}) & \text{if } n=1 \\ \max\{d(k), d(n-k)\} + d(\text{AND}) & \text{otherwise.} \end{cases}$$

Set  $k = n/2$ . It follows that  $d(n) = \Theta(\log n)$ .

$$d(n) = \begin{cases} 1 & n=1 \\ d(\lfloor \frac{n}{2} \rfloor) + 1 & \text{o.w.} \end{cases}$$

## Theorem

For every decoder  $G$  of input length  $n$ :

$$d(G) = \Omega(\log n)$$

$$c(G) = \Omega(2^n).$$

## Proof.

- 1 lower bound on delay : use log delay lower bound theorem.
- 2 lower bound on cost? The proof is based on the following observations:
  - Computing each output bit requires at least one nontrivial gate.
  - No two output bits are identical.



delay : focus on  $Y[0]$

$$y[0] = 1 \Leftrightarrow \langle x \rangle = 0$$

$$\Leftrightarrow \text{OR}_n(x_{n-1}, \dots, x_0) = 0$$

$$|\text{cone}(y[0])| = n \Rightarrow \text{delay} \geq \log_2 n$$

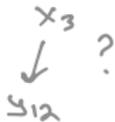
cost : want to prove cost  $\geq 2^n$

we have  $2^n$  distinct outputs:

$$\forall i \neq j \exists x : y[i] \neq y[j]$$



$$\forall i \forall j \exists x : y[i] \neq x[j]$$



$\Rightarrow \{Y[i]\}_{i=0}^{2^n-1}$  are outputs of different gates (that are not inputs)

- An encoder implements the inverse Boolean function implemented by a decoder.
- the Boolean function implemented by a decoder is not surjective.
- the range of the Boolean function implemented by a decoder is the set of binary vectors in which exactly one bit equals 1.
- It follows that an encoder implements a partial Boolean function (i.e., a function that is not defined for every binary string).

# Hamming Distance and Weight

## Definition

The **Hamming distance** between two binary strings  $u, v \in \{0, 1\}^n$  is defined by

$$\text{dist}(u, v) \triangleq |\{i \mid u_i \neq v_i\}|.$$

## Definition

The **Hamming weight** of a binary string  $u \in \{0, 1\}^n$  equals  $\text{dist}(u, 0^n)$ . Namely, the number of non-zero symbols in the string.

We denote the Hamming weight of a binary string  $\vec{a}$  by  $\text{wt}(\vec{a})$ , namely,

$$\text{wt}(a[n-1:0]) \triangleq |\{i : a[i] \neq 0\}|.$$

$$\text{dist}(000, 110) = 2, \quad \text{wt}(101) = 2$$

# Concatenation of strings

Recall that the concatenation of the strings  $a$  and  $b$  is denoted by  $a \circ b$ .

## Definition

The binary string obtained by  $i$  concatenations of the string  $a$  is denoted by  $a^i$ .

Consider the following examples of string concatenation:

- If  $a = 01$  and  $b = 10$ , then  $a \circ b = 0110$ .
- If  $a = 1$  and  $i = 5$ , then  $a^i = 11111$ .
- If  $a = 01$  and  $i = 3$ , then  $a^i = 010101$ .
- We denote the zeros string of length  $n$  by  $0^n$ .

# Definition of Encoder function

We define the encoder partial function as follows.

## Definition

The function  $\text{ENCODER}_n : \{\vec{y} \in \{0, 1\}^{2^n} : wt(\vec{y}) = 1\} \rightarrow \{0, 1\}^n$  is defined as follows:  $\langle \text{ENCODER}_n(\vec{y}) \rangle$  equals the index of the bit of  $y[2^n - 1 : 0]$  that equals one. Formally,

$$\text{ENCODER}_n(\underbrace{0^{2^n-k-1}}_{\text{MSB}} \circ \underbrace{1 \circ 0^k}_{\text{LSB}}) = \text{bin}_n(k)$$

Examples:

$$\begin{array}{l} \textcircled{1} \text{ ENCODER}_2(\overset{3}{0}\overset{2}{0}\overset{1}{0}\overset{0}{1}) = 00, \text{ ENCODER}_2(\overset{3}{0}\overset{2}{0}\overset{1}{1}\overset{0}{0}) = 01, \\ \text{ ENCODER}_2(\overset{3}{0}\overset{2}{1}\overset{1}{0}\overset{0}{0}) = 10, \text{ ENCODER}_2(\overset{3}{1}\overset{2}{0}\overset{1}{0}\overset{0}{0}) = 11. \\ \overset{3}{3}\overset{2}{2}\overset{1}{1}\overset{0}{0} \qquad \qquad \qquad \overset{3}{3}\overset{2}{2}\overset{1}{1}\overset{0}{0} \end{array}$$

## Definition

An **encoder** with input length  $2^n$  and output length  $n$  is a combinational circuit that implements the Boolean function  $\text{ENCODER}_n$ .

We denote an encoder with input length  $2^n$  and output length  $n$  by  $\text{ENCODER}(n)$ . An  $\text{ENCODER}(n)$  can be also specified as follows:

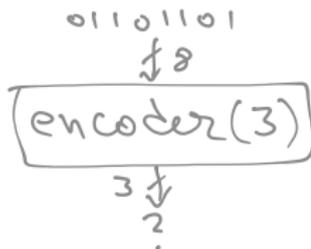
**Input:**  $y[2^n - 1 : 0] \in \{0, 1\}^{2^n}$ .

**Output:**  $x[n - 1 : 0] \in \{0, 1\}^n$ .

**Functionality:** If  $wt(\vec{y}) = 1$ , let  $i$  denote the index such that  $y[i] = 1$ . In this case  $\vec{x}$  should satisfy  $\langle \vec{x} \rangle = i$ .  
Formally:

$$\vec{x} = \text{ENCODER}_n(\vec{y}) .$$

- functionality is not specified for all inputs  $\vec{y}$ .
- functionality is only specified for inputs whose Hamming weight equals one.
- Since an encoder is a combinational circuit, it implements a Boolean function. This means that it outputs a digital value even if  $wt(y) \neq 1$ . Thus, two encoders must agree only with respect to inputs whose Hamming weight equals one.
- If  $\vec{y}$  is output by a decoder, then  $wt(\vec{y}) = 1$ , and hence an encoder implements the inverse function of a decoder.



# Brute Force Implementation

$$\begin{aligned} \text{bin}_3(5) &= 101 \\ \text{bin}_3(5)[1] &= 0 \end{aligned}$$

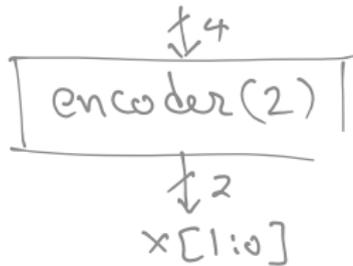
Recall that  $\text{bin}_n(i)[j]$  denotes the  $j$ th bit in the binary representation of  $i$ . Let  $A_j$  denote the set

$$A_j \triangleq \{i \in [0 : 2^n - 1] \mid \text{bin}_n(i)[j] = 1\}.$$

## Claim

If  $\text{wt}(y) = 1$ , then  $x[j] = \bigvee_{i \in A_j} y[i]$ .

$y[3:0]$  example  $(n=2)$



$\text{wt}(y) = 1:$

3	2	1	0	x
0	0	0	1	00
0	0	1	0	01
0	1	0	0	10
1	0	0	0	11

$$A_0 \triangleq \{ i \in [0:3] \mid \text{bin}_2(i)[0] = 1 \}$$

$$= \{ 1, 3 \} \quad (A_0 = \{ i \mid i \text{ odd} \})$$

$$A_1 \triangleq \{ i \in [0:3] \mid \text{bin}_2(i)[1] = 1 \}$$

$$= \{ 2, 3 \}$$

$$X_0 = Y_1 + Y_3 \quad X_1 = Y_2 + Y_3$$

$$\text{wt}(Y) = 1 \quad \& \quad x[j] = \bigvee_{i \in A_j} Y[i] \Rightarrow Y[\langle x \rangle] = 1$$

proof: Let  $l$  denote the unique index for which  $Y[l] = 1$ .

case 1:  $l = 0$ : Note that  $\forall_j: 0 \notin A_j$ .  
 $\Rightarrow x = 0^n$ , as req.

case 2:  $l > 0$ :  $x[j] = 1 \Leftrightarrow l \in A_j$   
but  $l \in A_j \Leftrightarrow \text{bin}_n(l)[j] = 1$

if  $\text{bin}_n(l)[j] = 1 \Rightarrow l \in A_j \Rightarrow x[j] = 1$

if  $\text{bin}_n(l)[j] = 0 \Rightarrow l \notin A_j \Rightarrow x[j] = 0$

$\Rightarrow \langle x \rangle = l$ , as required.



## Claim

If  $\text{wt}(y) = 1$ , then  $x[j] = \bigvee_{i \in A_j} y[i]$ .

Implementing an  $\text{ENCODER}(n)$ :

- For each output  $x_j$ , use a separate OR-tree whose inputs are  $\{y[i] \mid i \in A_j\}$ .
- Each such OR-tree has at most  $2^n$  inputs.
- the cost of each OR-tree is  $O(2^n)$ .
- total cost is  $O(n \cdot 2^n)$ . (in fact,  $\Theta(n \cdot 2^n)$ )
- The delay of each OR-tree is  $O(\log 2^n) = O(n)$ .

$$Q : |A_j| = \frac{2^n}{2}$$

# Can we do better?

graphical

- We will prove that the  $\checkmark$  cone of the first output is  $\Omega(2^n)$ .
- So for every encoder  $C$ :  $c(C) = \Omega(2^n)$  and  $d(C) = \Omega(n)$ .
- The brute force design is not that bad. Can we reduce the cost?
- Let's try...

# ENCODER'(n) - a recursive design

For  $n = 1$ , is simply  $x[0] \leftarrow y[1]$ .

**Reduction step:**

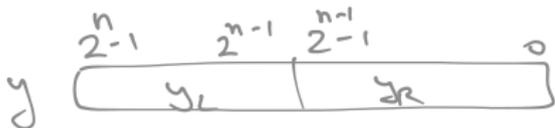
$$y_L[2^{n-1} - 1 : 0] = y[2^n - 1 : 2^{n-1}]$$

$$y_R[2^{n-1} - 1 : 0] = y[2^{n-1} - 1 : 0].$$

Use two ENCODER'(n - 1) with inputs  $\vec{y}_L$  and  $\vec{y}_R$ . But,

$$wt(\vec{y}) = 1 \Rightarrow (wt(\vec{y}_L) = 0) \vee (wt(\vec{y}_R) = 0).$$

What does an encoder output when input all-zeros?

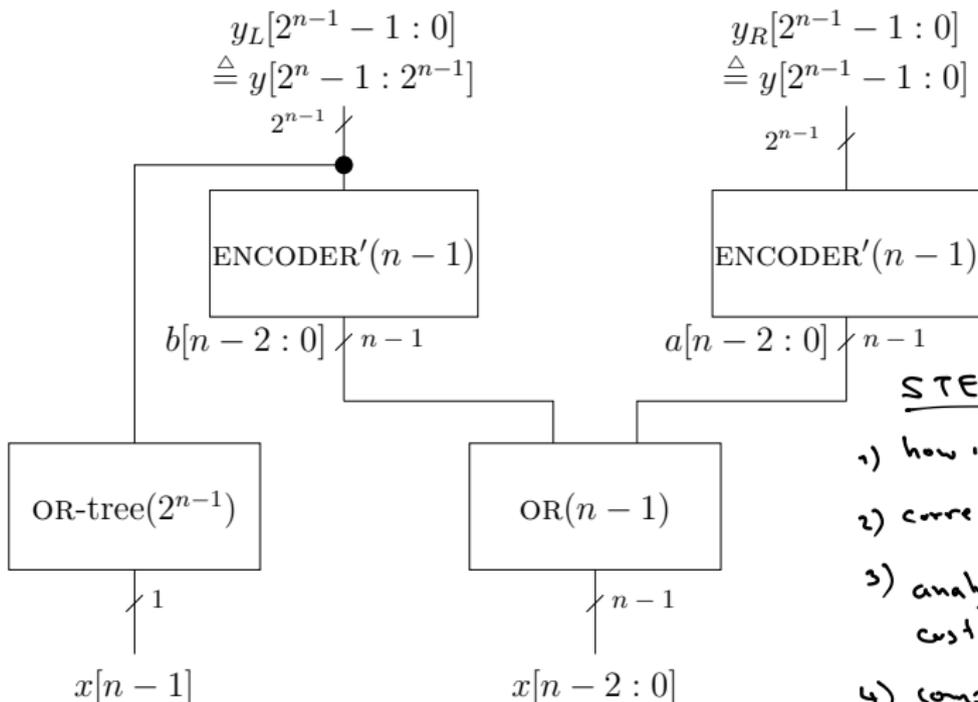


Augment the definition of the  $\text{ENCODER}_n$  function so that its domain also includes the all-zeros string  $0^{2^n}$ . We define

$$\text{ENCODER}_n(0^{2^n}) \triangleq 0^n.$$

Note that  $\text{ENCODER}'(1)$  (i.e.,  $x[0] \leftarrow y[1]$ ) also meets this new condition, so the induction basis of the correctness proof holds.

# Reduction step for ENCODER'(n)



## STEPS

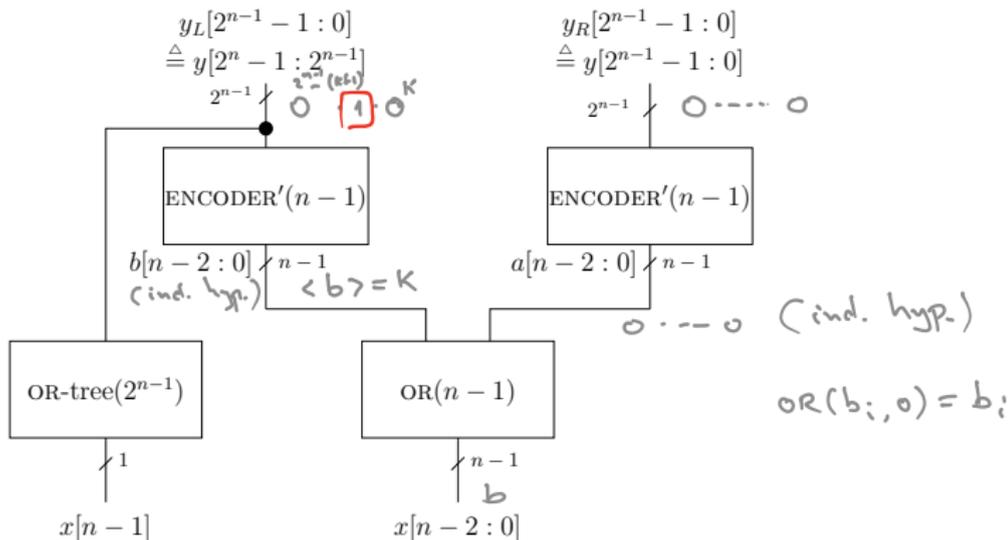
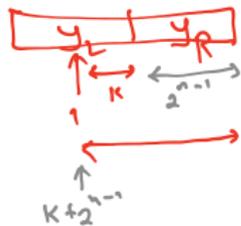
- 1) how it works?
- 2) correctness proof.
- 3) analysis of cost & delay
- 4) compare cost & delay with lower bounds

## Claim

The circuit  $\text{ENCODER}'(n)$  implements the Boolean function  $\text{ENCODER}_n$ .

Cases i

- ex.  $\left\{ \begin{array}{l} 1) y = 0^{2^n} \\ 2) w+(y_R) = 1 \\ \quad w+(y_L) = 0 \\ 3) w+(y_L) = 1 \\ \quad w+(y_R) = 0 \end{array} \right.$



output:  $\langle 10b \rangle = 2^{n-1} + \langle b \rangle = 2^{n-1} + K$

$$c(\text{ENCODER}'(n)) = \begin{cases} 0 & \text{if } n = 1 \\ 2 \cdot c(\text{ENCODER}'(n-1)) \\ \quad + c(\text{OR-tree}(2^{n-1})) \\ \quad + (n-1) \cdot c(\text{OR}) & \text{if } n > 1. \end{cases}$$

Let  $c(n) \triangleq c(\text{ENCODER}'(n))/c(\text{OR})$ .

$$c(n) = \begin{cases} 0 & \text{if } n = 1 \\ 2 \cdot c(n-1) + (2^{n-1} - 1 + n - 1) & \text{if } n > 1. \end{cases} \quad (2)$$

## Claim

$$c(n) = \Theta(n \cdot 2^n).$$

So  $c(\text{ENCODER}'(n))$  (asymptotically) equals the cost of the brute force design...

Solve:  $c(n) = 2 \cdot c(n-1) + \Theta(2^n)$

Recall:  $f(2^n) \stackrel{\Delta}{=} c(n)$

$$f(2^n) = 2 \cdot f(2^{n-1}) + \Theta(2^n)$$

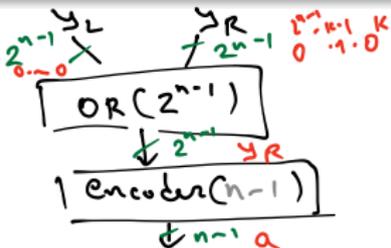
$$\begin{aligned} \Rightarrow f(2^n) &= \Theta(2^n \cdot \log 2^n) \\ &= \Theta(2^n \cdot n) \end{aligned}$$

$$\Rightarrow c(n) = \Theta(2^n \cdot n)$$



# Reducing The Cost

LHS

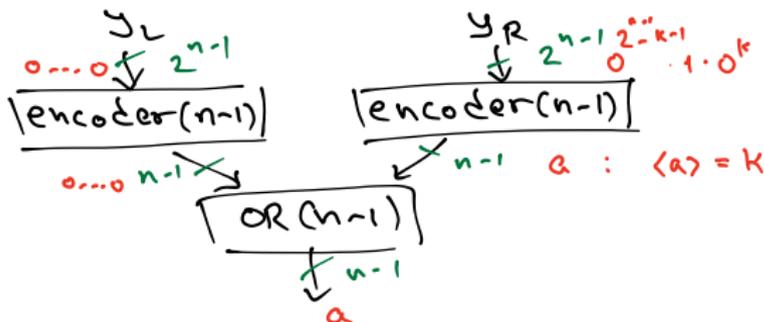


## Claim

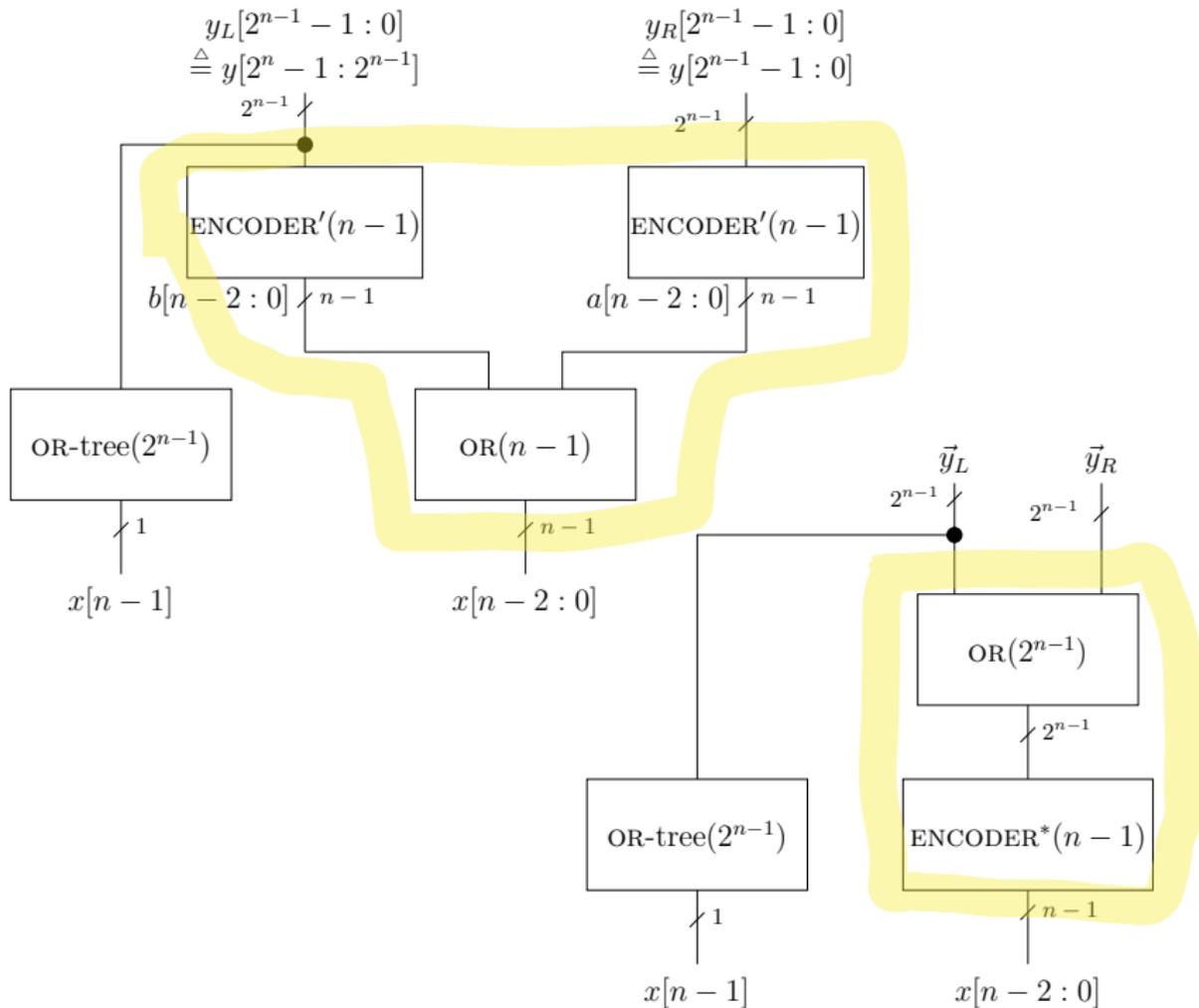
If  $\text{wt}(y[2^n - 1 : 0]) \leq 1$ , then

$$\begin{aligned} \text{ENCODER}_{n-1}(\text{OR}(\vec{y}_L, \vec{y}_R)) \\ = \text{OR}(\text{ENCODER}_{n-1}(\vec{y}_L), \text{ENCODER}_{n-1}(\vec{y}_R)). \end{aligned}$$

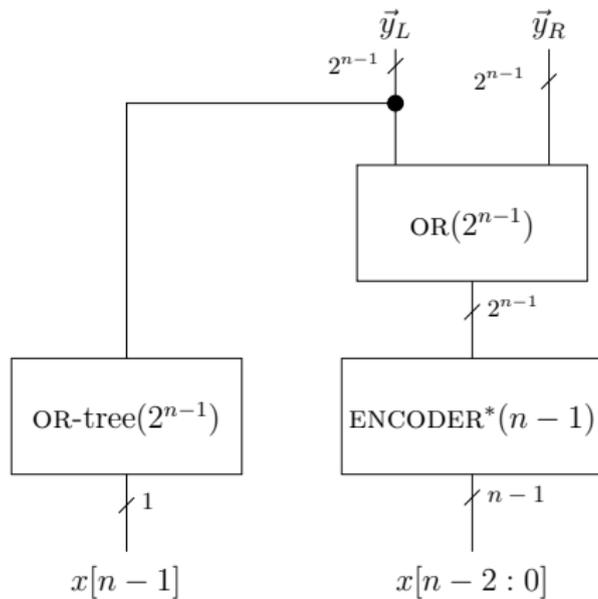
RHS



- ex.  $\begin{cases} 1) \text{ wt}(y) = 0 \\ 2) \text{ wt}(y_R) = 0 \text{ \& } \text{wt}(y_L) = 1 \\ 3) \text{ wt}(y_R) = 1 \text{ \& } \text{wt}(y_L) = 0 \end{cases}$



# Correctness?



# Functional Equivalence

## Definition

Two combinational circuits are **functionally equivalent** if they implement the same Boolean function.

## Claim

*If  $\text{wt}(y[2^n - 1 : 0]) \leq 1$ , then*

$$\text{ENCODER}_{n-1}(\text{OR}(\vec{y}_L, \vec{y}_R)) = \text{OR}(\text{ENCODER}_{n-1}(\vec{y}_L), \text{ENCODER}_{n-1}(\vec{y}_R)).$$

## Claim

*$\text{ENCODER}'(n)$  and  $\text{ENCODER}^*(n)$  are functionally equivalent.*

## Corollary

*$\text{ENCODER}^*(n)$  implements the  $\text{ENCODER}_n$  function.*

# Cost analysis

The cost of  $\text{ENCODER}^*(n)$  satisfies the following recurrence equation:

$$c(\text{ENCODER}^*(n)) = \begin{cases} 0 & \text{if } n=1 \\ c(\text{ENCODER}^*(n-1)) + (2^n - 1) \cdot c(\text{OR}) & \text{otherwise} \end{cases}$$

$C(2^k) \triangleq c(\text{ENCODER}^*(k))/c(\text{OR})$ . Then,

$$C(2^k) = \begin{cases} 0 & \text{if } k=0 \\ C(2^{k-1}) + (2^k - 1) \cdot c(\text{OR}) & \text{otherwise.} \end{cases}$$

$f(n) = 5(\frac{n}{2}) + \theta(n)$   
 $\Downarrow$   
 $f(n) = \theta(n)$

we conclude that  $C(2^k) = \Theta(2^k)$ .

## Claim

$$c(\text{ENCODER}^*(n)) = \Theta(2^n) \cdot c(\text{OR}).$$

The delay of  $\text{ENCODER}^*(n)$  satisfies the following recurrence equation:

$$d(\text{ENCODER}^*(n)) = \begin{cases} 0 & \text{if } n=1 \\ \max\{d(\text{OR-tree}(2^{n-1})), \\ d(\text{ENCODER}^*(n-1) + d(\text{OR}))\} & \text{otherwise.} \end{cases}$$

Since  $d(\text{OR-tree}(2^{n-1})) = (n-1) \cdot d(\text{OR})$ , it follows that

$$d(\text{ENCODER}^*(n)) = \cancel{n} \cdot d(\text{OR}).$$

(n-1)

$$d(n) = d(n-1) + 1 \quad \Rightarrow \quad d(n) = n-1$$

## Theorem

For every encoder  $G$  of input length  $n$ :

$$d(G) = \Omega(n)$$

$$c(G) = \Omega(2^n).$$

## Wrong Proof:

Focus on the output  $x[0]$  and the Boolean function  $f_0$  that corresponds to  $x[0]$ . Tempting to claim that  $|cone(f_0)| \geq 2^{n-1}$ , and hence the lower bounds follow.

But, this is not a valid argument because the specification of  $f_0$  is a partial function (domain consists only of inputs whose Hamming weight equals one)... must come up with a correct proof!

# Asymptotic Optimality

## Theorem

For every encoder  $G$  of ~~input~~ <sup>output</sup> length  $n$ :

$$d(G) = \Omega(n)$$

$$c(G) = \Omega(2^n).$$

$x[0] = OR_{2^{n/2}}(\{Y[i] \mid i \in A\})$   
func. cone considerations  
tricky because input  
is restricted!

## Proof.

Consider the output  $x[0]$ . We claim that

$$|cone_G(x[0])| \geq \frac{1}{2} \cdot 2^n.$$

for  $e_i$ :  $x[0]$  should = 0  
for  $e_j$ :  $x[0]$  should = 1  
 $0 = flip_i(e_i)$        $flip_j(e_j) = 0^{2^n}$

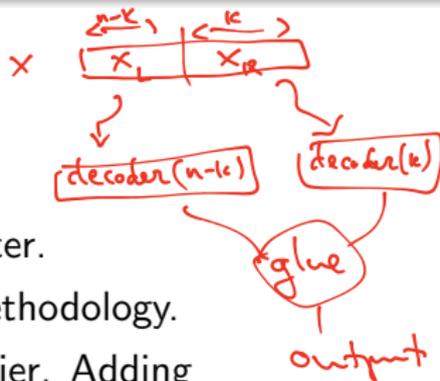
Otherwise, there exists an even index  $i$  and an odd index  $j$  such that  $\{i, j\} \cap cone_G(x[0]) = \emptyset$ . Now consider two inputs:  $e_i$  (a unit vector with a one in position  $i$ ) and  $e_j$ . The output  $x[0]$  is the same for  $e_i$ ,  $0^{2^n} = flip_i(e_i) = flip_j(e_j)$  and  $e_j$ . This implies that  $x[0]$  errs for at least of the inputs  $e_i$  or  $e_j$ .  $\square$

# Parametric Specification

- The specification of  $\text{DECODER}(n)$  and  $\text{ENCODER}(n)$  uses the parameter  $n$ .
- The parameter  $n$  specifies the length of the input. *in a decoder*
- $\text{DECODER}(8)$  and  $\text{DECODER}(16)$  are completely different circuits.
- $\{\text{DECODER}(n)\}_{n=1}^{\infty}$  is a family of circuits, one for each input length.

We discussed:

- buses
- decoders
- encoders



Three main techniques were used in this chapter.

- Divide & Conquer - a recursive design methodology.
- Extend specification to make problem easier. Adding restrictions to the specification made the task easier since we were able to add assumptions in our recursive designs.
- Evolution. Naive, correct, costly design. Improved while preserving functionality to obtain a cheaper design.

$$\text{spec: } wt(y) = 1$$

$$\text{extended spec: } wt(y) \leq 1$$