

Digital Logic Design: a rigorous approach ©

Chapter 9: Representation of Boolean Functions by Formulas

Guy Even Moti Medina

School of Electrical Engineering Tel-Aviv Univ.

April 20, 2020

Book Homepage:

<http://www.eng.tau.ac.il/~guy/Even-Medina>

Normal Forms of Boolean Functions

- A **normal form** is a restricted syntax for Boolean Formulas.
- For example, Negation Normal Form (NNF) allows negations only of variables or constants.
- We now consider two more normal forms:
 - Disjunctive Normal Form (DNF) also called Sum of Products (SoP)
 - Conjunctive Normal Form (CNF) also called Product of Sums (PoS)
- We will also consider polynomials over a finite field!

Definition (literal)

A variable or a negation of a variable is called a **literal**.

Example

- X
- $\text{NOT}(X)$

Recall that:

- AND, \cdot , \wedge denote the same logical connective.
- Associativity of AND function allows us to omit parenthesis.

Definition (product/conjunction)

A Boolean formula φ is a **conjunction** (or a **product**) if

$$\varphi = l_1 \text{ AND } \cdots \text{ AND } l_k,$$

for $k \geq 1$ and every l_i is a literal.

Example

$$\begin{aligned} X \cdot \bar{Y} \cdot Z &= (X \text{ AND } \bar{Y} \text{ AND } Z) \\ &= (X \wedge \bar{Y} \wedge Z) \end{aligned}$$

- With each product p , we associate the set of variables that appear in p .
- The set of variables that appear in p is denoted by $vars(p)$.
- Let $vars^+(p)$ denote the set of variables that appear in p that appear without negation.
- Let $vars^-(p)$ denote the set of variables that appear in p that with negation.
- Let $literals(p)$ denote the set of literals that appear in p .
- $p = \bigwedge_{\ell \in literals(p)} \ell = (\bigwedge_{X_i \in vars^+(p)} X_i) \text{ AND } (\bigwedge_{X_i \in vars^-(p)} \bar{X}_i)$.

Example

Let $p = X_1 \cdot \bar{X}_2 \cdot X_3$, then $vars(p) = \{X_1, X_2, X_3\}$,
 $vars^+(p) = \{X_1, X_3\}$ and $vars^-(p) = \{X_2\}$, and
 $literals(p) = \{X_1, \bar{X}_2, X_3\}$.

Simple Products

Definition (simple product)

A product term p is **simple** if every variable appears at most once in p .

a simple product: $X_1 \cdot X_2 \cdot \bar{X}_3$

not simple: $X \cdot X$, $X_1 \cdot X_2 \cdot \bar{X}_1$

Recall that:

- 1 $X \cdot \bar{X}$ is a contradiction
- 2 $X \cdot X$ is logically equivalent to X
- 3 $\bar{X} \cdot \bar{X}$ is logically equivalent to \bar{X} .

Claim

Every product is a contradiction or logically equivalent to a simple product.

exercise!

Definition (minterm)

A simple product term p is a **minterm** with respect to a set U of variables if $\text{vars}(p) = U$.

Example

$U = \{X, Y, Z\}$. Minterms: $X \cdot Y \cdot Z$, $\bar{X} \cdot \bar{Y} \cdot Z$.

question

How many different minterms are there with respect to U ?

lemma

A minterm p attains the truth value 1 for exactly one truth assignment.

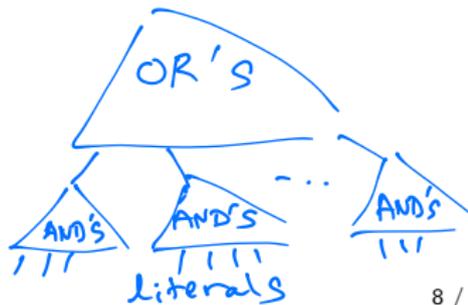
Sum-of-Products (SOP) / Disjunctive Normal Form (DNF)

Definition (SoP/DNF)

A Boolean formula φ is called a **sum-of-products** (SOP) (or in **Disjunctive Normal Form** (DNF)) if satisfies one of the following conditions:

- 1 $\varphi = p_1 + \dots + p_k$, where $k \geq 2$ and each p_i is a product
- 2 φ is a product

(the case of a product is a degenerate case for $k = 1$ and includes the case of a single literal.)



Each of the following formulas is a sum-of-products.

① $\varphi_1 = X \cdot Y + X \cdot Y,$

② $\varphi_2 = (\bar{A} \text{ AND } B \text{ AND } C) \text{ OR } (A \text{ AND } \bar{B} \text{ AND } C) \text{ OR } \bar{D},$

③ $\varphi_3 = L.$

Each of the following formulas is **not** a sum-of-products.

① $(X + Y) \cdot Z,$

② $(A \text{ OR } B) \text{ AND } (C \text{ OR } D).$

Definition

For a $v \in \{0, 1\}^n$, define the minterm p_v to be $p_v \triangleq (l_1^v \cdot l_2^v \cdots l_n^v)$, where:

$$l_i^v \triangleq \begin{cases} X_i & \text{if } v_i = 1 \\ \bar{X}_i & \text{if } v_i = 0. \end{cases}$$

$$v = 011$$

$$p_v = \bar{X}_1 \cdot X_2 \cdot X_3$$

Question

What is the truth assignment that satisfies p_v ?

Question

Prove that the mapping $v \mapsto p_v$ is a bijection from $\{0, 1\}^n$ to the set of all minterms. (over $\{x_1, \dots, x_n\}$)

Definition (preimage)

Let $f : \{0, 1\}^n \rightarrow \{0, 1\}$. Let $f^{-1}(1)$ denote the set

$$f^{-1}(1) \triangleq \{v \in \{0, 1\}^n \mid f(v) = 1\}.$$

Definition

The set of minterms of f is defined by

$$\text{Min}(f) \triangleq \{p_v \mid v \in f^{-1}(1)\}.$$

truth table of $f: \{0,1\}^2 \rightarrow \{0,1\}$

x_1 x_2 $f(x_1, x_2)$

0 0 0

0 1 1

1 0 1

1 1 0

$$f^{-1}(1) = \begin{array}{|cc|} \hline 0 & 1 \\ \hline 1 & 0 \\ \hline \end{array}$$

$$\text{min}(f) = \{ p_{01}, p_{10} \}$$

$$= \{ \bar{x}_1 \cdot x_2, x_1 \cdot \bar{x}_2 \}$$

check that: $\bar{x}_1 \cdot x_2 + x_1 \cdot \bar{x}_2$
expresses f

Theorem

Every Boolean function $f : \{0, 1\}^n \rightarrow \{0, 1\}$ that is not a constant zero is expressed by the sum of the minterms in $Min(f)$.

Question

Let φ be the sum of the minterms in $Min(f)$ and let τ denote a truth assignment that satisfies φ (i.e., $\hat{\tau}(\varphi) = 1$). How many products in φ are satisfied by τ ?

THM: $\sum_{P \in \text{Min}(f)} P$ expresses f

proof:

consider $v \in \{0,1\}^n$.

if $f(v) = 1$, then

$$P_v \in \text{Min}(f)$$

P_v satisfied by τ_v ($\hat{\tau}_v(P_v) = 1$)

$$\Rightarrow \hat{\tau}_v\left(\sum_{P \in \text{Min}(f)} P\right) = 1$$

if $f(v) = 0$, then

$$\forall P \in \text{Min}(f) : \hat{\tau}_v(P) = 0$$

$$\Rightarrow \hat{\tau}_v\left(\sum_{P \in \text{Min}(f)} P\right) = 0$$



sum-of-minterms: a “bad” example

We are interested in “short” formulas that express a given Boolean function.

- Consider the constant Boolean function $f : \{0, 1\}^n \rightarrow \{0, 1\}$ that is defined by $f(v) = 1$, for every v .
- The sum-of-minterms that represents f is the sum of all the possible minterms over n variables. This sum contains 2^n minterms.
- On the other hand, f can be represented by the constant 1.
- The question of finding the shortest sum-of-products that represents a given Boolean formula is discussed in more detail in our book. (unfortunately, no efficient optimization is believed to exist)

The second normal form we consider is called **conjunctive normal form** (CNF) or **product of sums** (POS).

Recall that:

- OR, +, \vee denote the same logical connective.
- Associativity of OR function allows us to omit parenthesis.

Definition

A Boolean formula s is a **disjunction** (or a **sum**) if

$$s = l_1 + \cdots + l_k,$$

for $k \geq 1$ and every l_j is a literal.

Example

$$\begin{aligned} X + \bar{Y} + Z &= (X \text{ OR } \bar{Y} \text{ OR } Z) \\ &= (X \vee \bar{Y} \vee Z) \end{aligned}$$

Define $\text{vars}(s)$, $\text{vars}^+(s)$, $\text{vars}^-(s)$, $\text{literals}(s)$ as in products.

Maxterms

Definition (simple sum)

A sum s is **simple** if every variable appears at most once in s .

Definition (maxterm)

A simple sum term s is a **maxterm** with respect to a set U of variables if $\text{vars}(s) = U$.

Question

How many maxterms are there with respect to U ?

Lemma

A maxterm s is satisfied by all but one truth assignment (s attains the truth value 0 for exactly one truth assignment).

$$x + \bar{y} + z \quad \tau(x) = 0 \quad \tau(y) = 1 \quad \tau(z) = 0$$

Definition (SoP/DNF)

A Boolean formula φ is called a **product-of-sums** (POS) (or in **Conjunctive Normal Form** (CNF)) if satisfies one of the following conditions:

- 1 $\varphi = s_1 \cdots \cdots s_k$, where $k \geq 2$ and each s_i is a sum
- 2 φ is a sum

AND'S

(the case of a sum is a degenerate case for $k = 1$ and includes the case of a single literal.)

Recall that $DM(\varphi)$ is the De Morgan dual of the formula φ .

observation

- 1 If p is a product, then $DM(p)$ is a sum.
- 2 If s is a sum, then $DM(s)$ is a product.
- 3 If p is a minterm, then $DM(p)$ is a maxterm.
- 4 If s is a maxterm, then $DM(s)$ is a minterm.
- 5 If p is a sum-of-products, then the formula $DM(p)$ is a product-of-sums.
- 6 If p is a product-of-sums, then the formula $DM(p)$ is a sum-of-products.

$$x_1 \cdot x_2 \cdot x_3 \xrightarrow{DM} \bar{x}_1 + \bar{x}_2 + \bar{x}_3$$

Maxterms of a Boolean Function

Definition

For a $v \in \{0, 1\}^n$, define the maxterm s_v to be $s_v \triangleq (m_1^v + \cdots + m_n^v)$, where:

$$m_i^v \triangleq \begin{cases} X_i & \text{if } v_i = 0 \\ \bar{X}_i & \text{if } v_i = 1. \end{cases}$$

Note that l_i^v is logically equivalent to $\text{NOT}(m_i^v)$.

Question

Which truth assignment does not satisfy s_v ?

$$\begin{aligned} \hat{c}(m_i^v) = 0 & : \text{ if } v_i = 0 : \hat{c}(X_i) = 0 \\ & \text{ if } v_i = 1 : \hat{c}(\bar{X}_i) = 0 \\ & \hat{c}(X_i) = 1 \end{aligned}$$

Definition (Maxterms of a function $f : \{0, 1\}^n \rightarrow \{0, 1\}$)

$$\text{Max}(f) \triangleq \{s_v \mid v \in f^{-1}(0)\} .$$

Theorem

Every Boolean function $f : \{0, 1\}^n \rightarrow \{0, 1\}$ that is not a constant one is expressed by the product of the maxterms in $\text{Max}(f)$.

De Morgan Duality and CNF representation

Question

What is the relation between $Min(f)$ and $Max(\text{NOT}(f))$?

Let $U = \{X_1, \dots, X_n\}$ and $f : \{0, 1\}^n \rightarrow \{0, 1\}$.

Lemma

Let p denote a minterm wrt U . Then,

$$p \in Min(f) \iff DM(p) \in Max(\text{NOT}(f))$$

Let s denote a maxterm wrt U . Then,

$$s \in Max(f) \iff DM(s) \in Min(\text{NOT}(f))$$

Theorem

$$CNF(f) = DM(DNF(\text{NOT}(f)))$$

Lemma: $p \in \text{Min}(f) \Rightarrow \text{DM}(p) \in \text{Max}(\bar{f})$

proof: (\Rightarrow) (converse exercise)

$p \in \text{Min}(f)$ means that

$$\exists v \in \{0,1\}^n : p = p_v \text{ \& } f(v) = 1$$

$$\text{but } \text{DM}(p_v) = s_v \text{ \& } \bar{f}(v) = 0$$

$$\Rightarrow \text{DM}(p) \in \text{Max}(\bar{f})$$

Lemma: $s \in \text{Max}(f) \Rightarrow \text{DM}(s) \in \text{Min}(f)$ □
exercise!

$$\text{THM: } \text{CNF}(f) = \text{DM}(\text{DNF}(\bar{f}))$$

Proof: (sketch)

$$f \xrightarrow{\text{not}} \bar{f}$$

$$\sum_{v \in S^{n(1)}} p_v \rightsquigarrow \text{DNF}(\bar{f}) \xrightarrow[\text{DM}]{\text{not}} \text{DM}(\text{DNF}(\bar{f}))$$

2 negations \Rightarrow

$$f \cong \underbrace{\text{DM}(\text{DNF}(\bar{f}))}_{\text{a CNF formula.}}$$

Definition

The **Galois Field** $GF(2)$ is defined as follows.

- 1 Elements: the elements of $GF(2)$ are $\{0, 1\}$. The zero is called the additive unity and one is called the multiplicative unity.
- 2 Operations:
 - 1 addition which is simply the XOR function, and
 - 2 multiplication which is simply the AND function.

In the context of $GF(2)$ we denote multiplication by \cdot and addition by \oplus .

We are used to infinite fields like the rationals (or reals) with regular addition and multiplication. In these fields, $1 + 1 \neq 0$. However, in $GF(2)$, $1 \oplus 1 = 0$.

Observation

$X \oplus X = 0$, for every $X \in \{0, 1\}$.

A minus sign in a field means the additive inverse.

Definition

The element $-X$ stands for the element Y such that $X \oplus Y = 0$.

Observation

In $GF(2)$, the additive inverse of X is X itself, namely $-X = X$, for every $X \in \{0, 1\}$.

Thus, we need not write minus signs, and adding an X is equivalent to subtracting an X .

The distributive law holds in $GF(2)$, namely:

Observation

$(X \oplus Y) \cdot Z = (X \cdot Z) \oplus (Y \cdot Z)$, for every $X, Y, Z \in \{0, 1\}$.

Let X^k denote the product (AND of literals)

$$X^k \triangleq \overbrace{X \cdots X}^{k \text{ times}}.$$

We define $X^0 = 1$, for every $X \in \{0, 1\}$. The following observation proves that multiplication is **idempotent**.

Observation

$X^k = X$, for every $k \in \mathbb{N}^+$ and $X \in \{0, 1\}$.

$GF(2)$ is a field like the reals

The structure of a field allows us to solve systems of equations. In fact, **Gauss elimination** works over any field. The definition of a vector space over $GF(2)$ is just like the definition of vector spaces over the reals. Definitions such as linear dependence, dimension of vector spaces, and even determinants apply also to vector spaces over $GF(2)$.

Examples



$$X_1 \oplus X_2 \oplus (-X_2) = -X_2 = X_2$$

Handwritten annotations: A bracket above the equation indicates that $X_1 \oplus X_2 \oplus (-X_2) = 0$. Another bracket below the equation indicates that $X_2 \oplus (-X_2) = X_2$.

$$X_1 \oplus X_2 = 0 \Leftrightarrow X_1 = X_2.$$

- We show how to solve a simple systems of equalities over $GF(2)$ using Gauss elimination. Consider the following system of equations

$$\begin{array}{l} 1) \quad X_1 \oplus X_2 \oplus X_3 = 0, \\ 2) \quad X_1 \oplus X_3 = 0, \\ 3) \quad X_2 \oplus X_3 = 1. \end{array}$$

(1+2) $X_2 = 0$

3) $\Rightarrow 0 \oplus X_3 = 1 \Rightarrow X_3 = 1$

Definition

A **monomial** in $GF(2)$ over the variables in the set U is a finite product of the elements in U or a constant in $\{0, 1\}$.

Observation

Every monomial p in $GF(2)$ over the variables in U equals a constant or a simple product of variables in p .

- By commutativity: $X_1 \cdot X_2 \cdot X_3 \cdot X_1 = X_1^2 \cdot X_2 \cdot X_3$.
- Positive exponents can be reduced to one. For example, $X_1^2 \cdot X_2 \cdot X_3$ equals $X_1 \cdot X_2 \cdot X_3$.

Definition

A **polynomial** in $GF(2)$ over the variables in the set U is a finite sum of monomials.

Example: $X_1 \cdot X_2 \oplus X_1 \cdot X_3 \oplus X_2 \cdot X_3 \oplus 1$.

We denote the set of all polynomials in $GF(2)$ over the variables in U by $GF(2)[U]$. Just as multivariate polynomials over the reals can be added and multiplied, so can polynomials in $GF(2)[U]$.

representation by polynomials in $GF(2)[U]$

Every polynomial $p \in GF(2)[U]$ is a Boolean function $f_p : \{0, 1\}^{|U|} \rightarrow \{0, 1\}$. The converse is also true.

$p(x) \neq \sin x$
 $p(x) \neq e^x$

Theorem

Every Boolean function $f : \{0, 1\}^n \rightarrow \{0, 1\}$ can be represented by a polynomial in $GF(2)[U]$, where $U = \{X_1, \dots, X_n\}$.

proof outline

- easy: f is constant.

- $f^{-1}(1) \triangleq \{v \in \{0, 1\}^n \mid f(v) = 1\}$.

$$x_1 \cdot \bar{x}_2 \cdot \bar{x}_3 \cdot x_4 = x_1 \cdot (1 \oplus x_2) \cdot (1 \oplus x_3) \cdot x_4$$

- For each $v \in f^{-1}(1)$, we define the product p_v . The polynomial $p \in GF(2)[U]$ is defined as follows.

not a monomial!

$$p \triangleq \bigoplus_{v \in f^{-1}(1)} p_v$$

XOR

$$DNF(f) = \sum_{v \in f^{-1}(1)} p_v$$

OR

Why can we replace OR by XOR?

$$\begin{aligned} \text{OR}(1, 1) &= 1 \\ \text{XOR}(1, 1) &= 0 \\ \text{OR}(0, \dots, 0, 1) &= 1 \\ \text{XOR}(0, \dots, 0, 1) &= 1 \end{aligned}$$

$$\forall f \exists \text{poly } p \in GF(2)[w] : p = f$$

Corollary

The set of connectives {XOR, AND} is complete.

Satisfiability

The problem of satisfiability of Boolean formulas is defined as follows.

Input: A Boolean formula φ .

$(x \cdot y \vee z) \cdot w \vee (\bar{x})$
(string / parse tree)

Output: The output should equal “yes” if φ is satisfiable. If φ is not satisfiable, then the output should equal “no”.

Note that the problem of satisfiability is quite different if the input is a truth table of a Boolean function. In this case, we simply need to check if there is an entry in which the function attains the value 1.



yes $\Leftrightarrow \exists$ truth assign τ
 $\hat{\tau}(\varphi) = 1$

The main open problem in Computer Science since 1971 is whether $P = NP$. We will not define the classes P and NP , but we will phrase an equivalent question in this section.

Consider a Boolean formula φ . Given a truth assignment τ , it is easy to check if $\hat{\tau}(\varphi) = 1$. We showed how this can be done in Algorithm EVAL. In fact, the running time of the EVAL algorithm is linear in the length of φ .

On the other hand, can we find a satisfying truth assignment by ourselves (rather than check if τ is a satisfying assignment)?

Clearly, we could try all possible truth assignments. However, if n variables appear in φ , then the number of truth assignments is 2^n .

We are ready to formulate a question that is equivalent to the question $P = NP$.

Satisfiability in polynomial time

Does there exist a constant $c > 0$ and an algorithm Alg such that:

- 1 Given a Boolean formula φ , algorithm Alg decides correctly whether φ is satisfiable.
- 2 The running time of Alg is $O(|\varphi|^c)$, where $|\varphi|$ denotes the length of φ .

This seemingly simple question turns out to be a very deep problem about what can be easily computed versus what can be easily proved. It is related to the question whether there is a real gap between checking that a proof is correct and finding a proof.